







Future Internet Winter Camp 2009

Session 4: 무선 테스트베드

GNU Radio를 이용한 Cognitive Radio Network 구현

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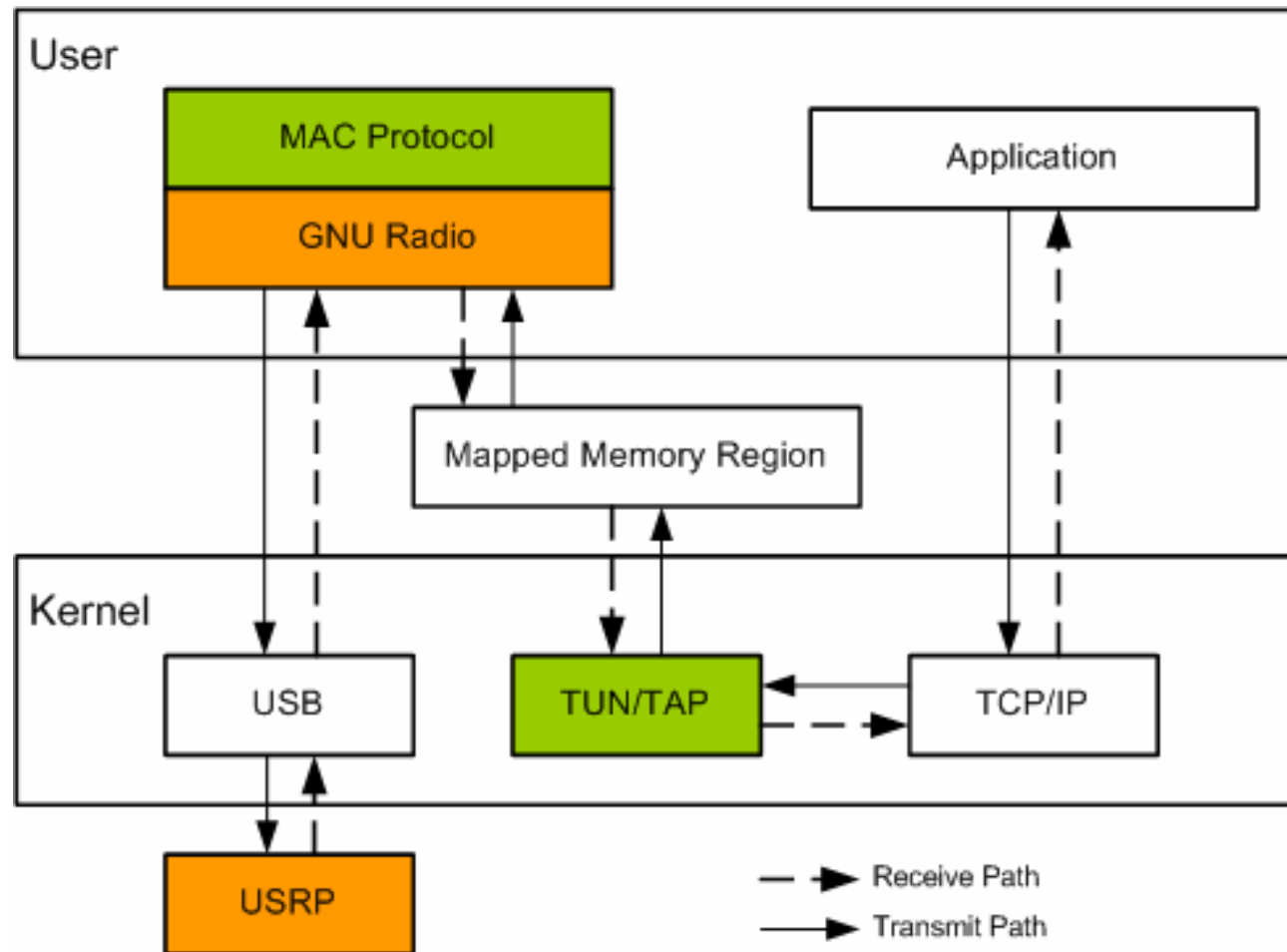
Introduction

◆ GNU Radio

- An open source software toolkit for building Software Defined Radio (SDR)
- Signal processing package
- Supports Linux and Mac OS
- Programming languages
 - C++
 - Performance critical applications
 - Signal processing blocks
 - Python
 - Using Python for creating flow graphs
 - Also used for creating GUI's
 - and other non performance critical applications

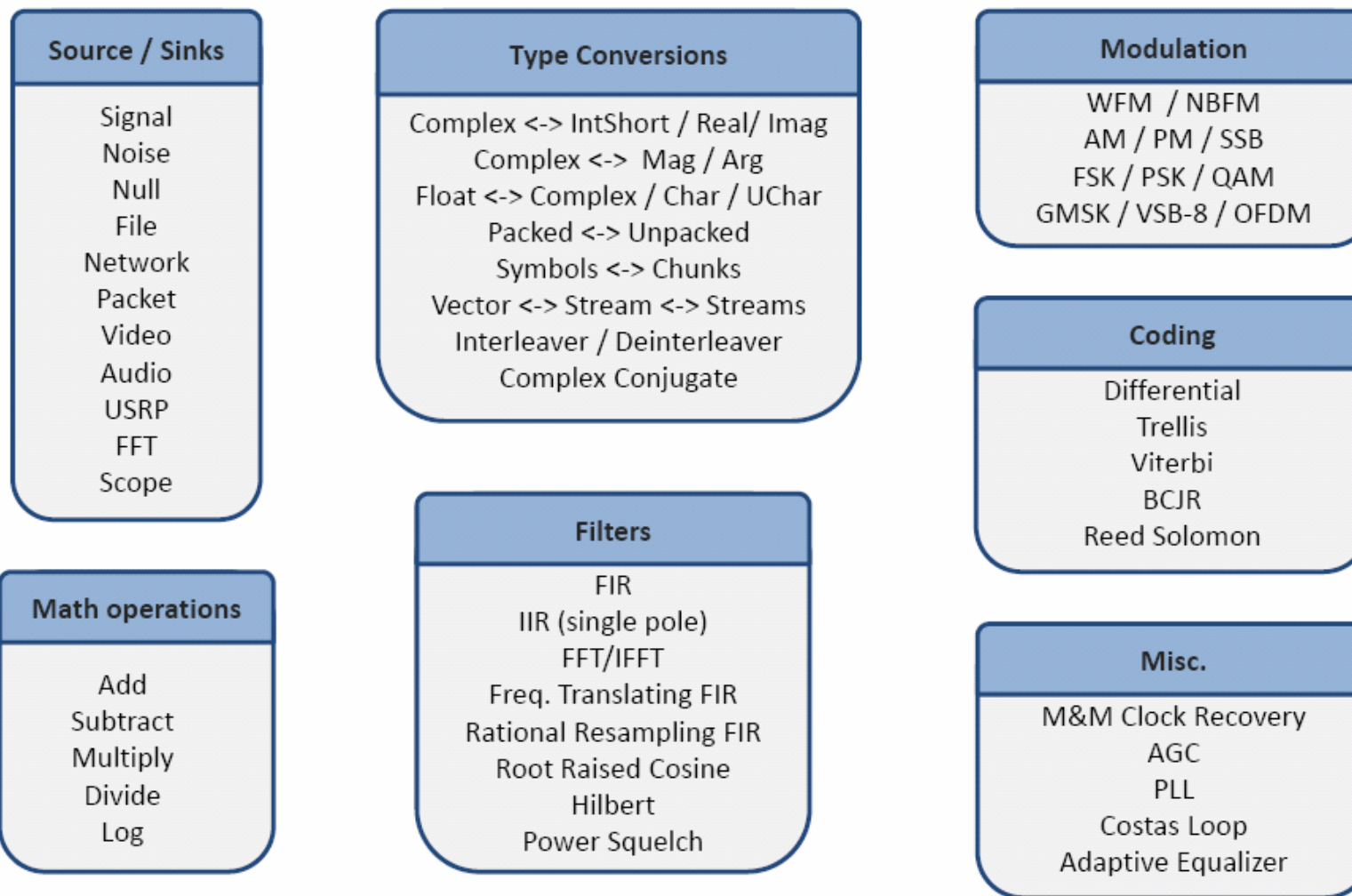
Introduction

◆ GNU Radio Data Path



Introduction

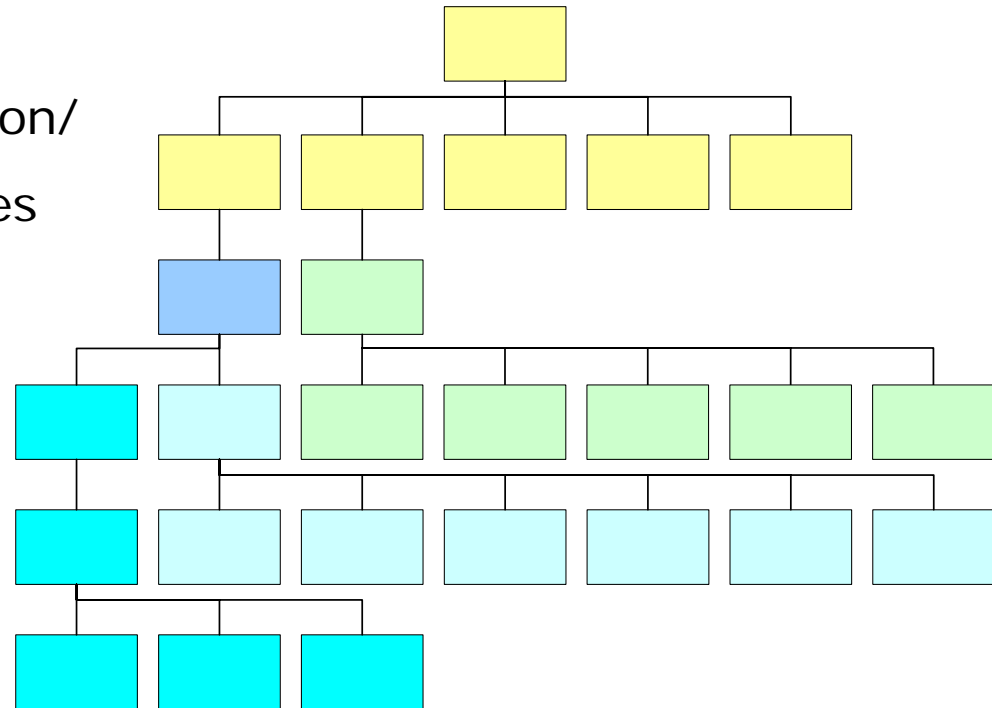
◆ Available GNU Radio Blocks



Introduction

◆ Directory Structure of GNU Radio

- /gr-utils/
 - Plotting
- /gnuradio-examples/python/
 - Execution example files
 - Written in Python
- /gnuradio-core/
 - lib
 - Core blocks
 - Written in C++
 - python
 - Python modules
 - Modulation, OFDM, Packetizing, etc.



Introduction

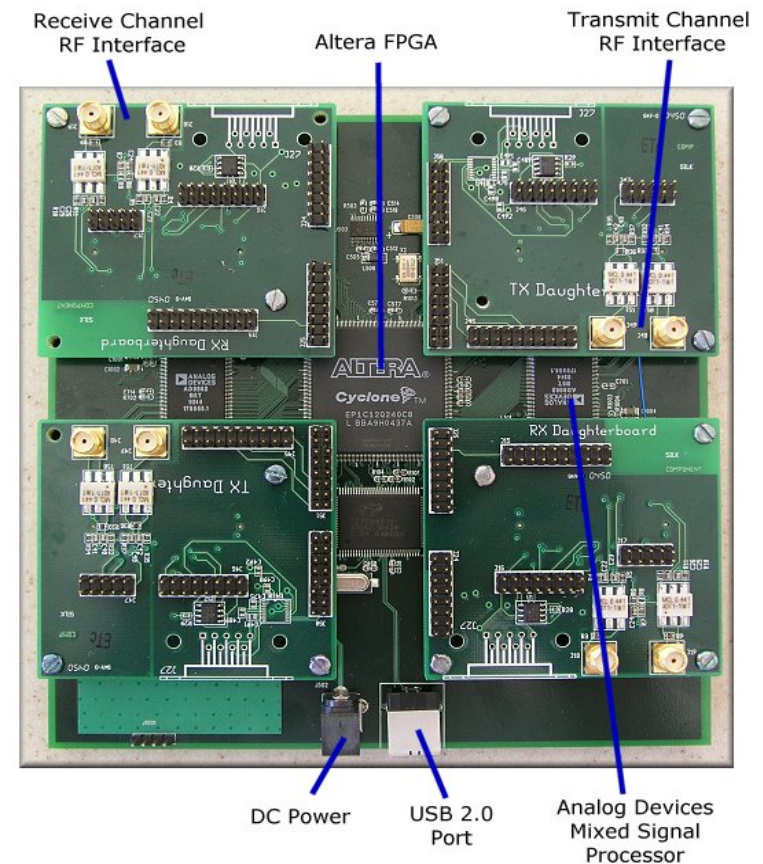
◆ GNU Radio Hardware Platform

■ Universal Software Radio Peripheral (USRP)

- The USRP is a device developed especially for GNU Radio

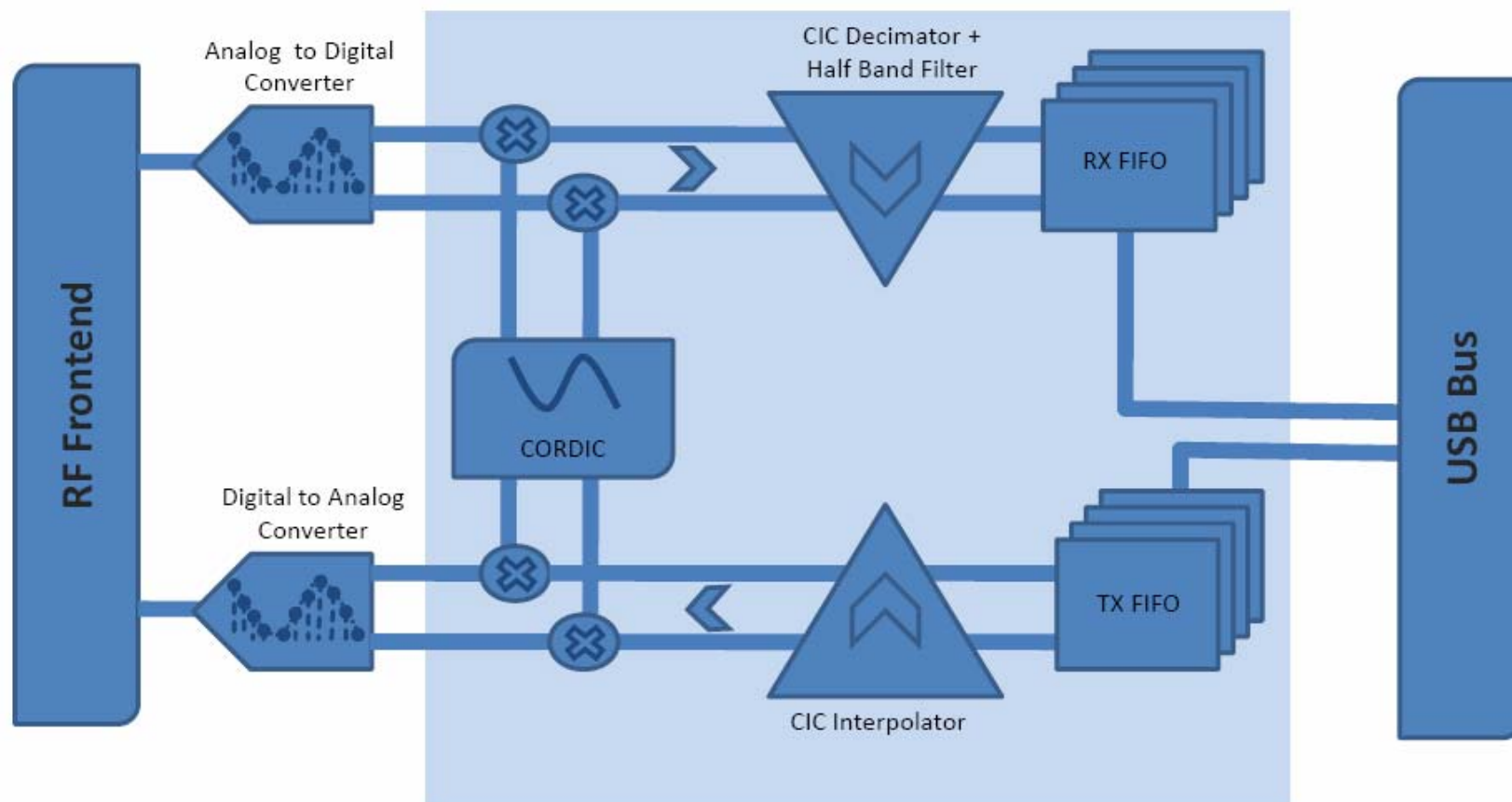
■ Supporting

- Two Receive daughter boards
- Two Transmit daughter boards
- Full duplex
- 4×ADC, 12 bit @ 64 MS/S
- 4×DAC, 14 bit @ 128 MS/S
- FPGA
- USB 2.0 interface to host PC
 - It can sustain 32 MB/sec



Introduction

◆ USRP Architecture



Introduction

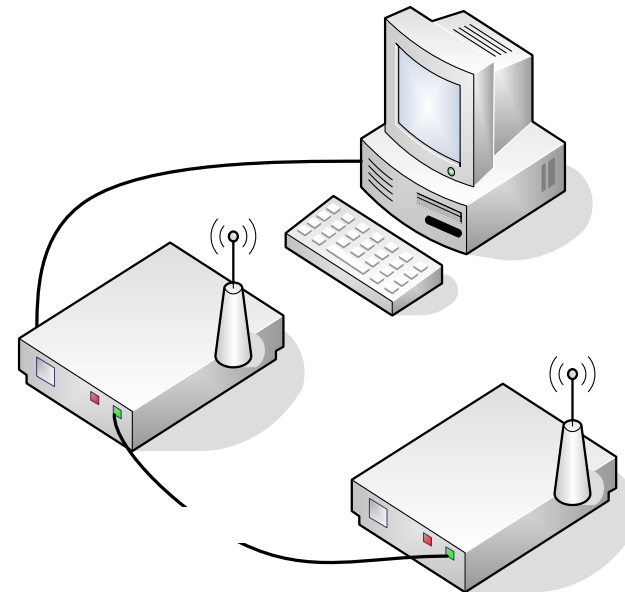
◆ USRP Daughter Boards

- RF frontend of USRP
 - Transceiver: RFX series
 - RFX400: 400-500 MHz, 100 mW output
 - RFX900: 800-1000 MHz, 200 mW output
 - RFX1200: 1150-1450 MHz, 200 mW output
 - RFX1800: 1.5-2.1 GHz, 100 mW output
 - RFX2400: 2.3-2.9 GHz, 20 mW output

Introduction

◆ USRP2

- Using gigabit Ethernet interface instead of USB 2.0 interface
 - Maximum bandwidth is not limited by interface between host and USRP2 anymore
 - Supporting 25 MHz bandwidth (8 MHz for USRP1) for one USRP device
 - A gigabit Ethernet interface can be used commonly for more than 2 USRP devices
 - Secondary USRP2 device can be connected with primary USRP2 device using MIMO cable



Introduction

◆ USRP2

- Possibly supports stand-alone mode in the future
 - It has a SD card
 - GNU radio does not support this yet
 - Being developing
 - Too long processing delay problem can be reduced if stand-alone mode is supported
- MIMO capability using multiple USRP2 boards
 - USRP2 has MIMO cable port to exchange clock and data among USRP2 boards
 - GNU radio software does not support this mode yet. It is under development now

Introduction

◆ USRP2

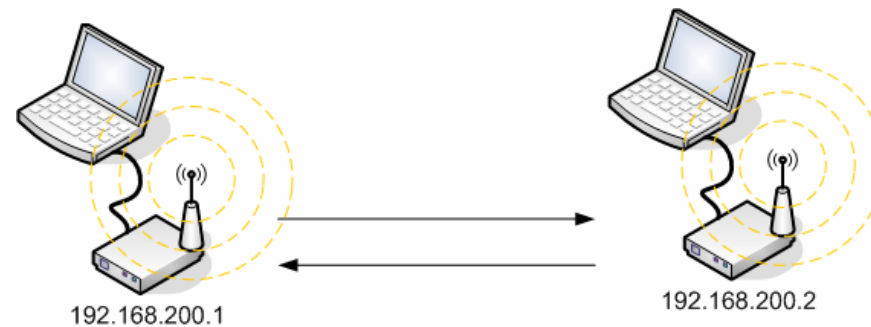


	USRP1	USRP2
Interface	USB 2.0	Gigabit Ethernet
FPGA	Altera EP1C12	Xilinx Spartan 3 2000
RF Bandwidth to/from host	8 MHz @ 16bits	25 MHz @ 16bits
Cost	\$700	\$1400
ADC Samples	12-bit, 64 MS/s	14-bit, 100 MS/s
DAC Samples	14-bit, 128 MS/s	16-bit, 400 MS/s
Daughterboard capacity	2 TX, 2 RX	1 TX, 1 RX
SRAM	None	1 Megabyte
Power	6V, 3A	6V, 3A

Implementation of CR Network

◆ Simple Performance

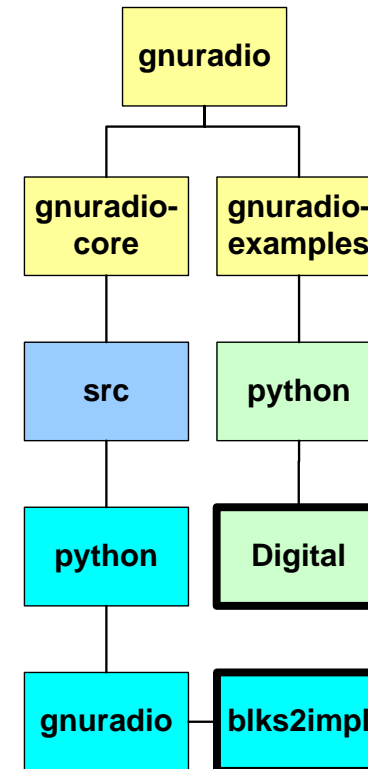
- Test environment
 - Ubuntu 8.10 (Kernel ver. 2.6.27)
 - Intel Pentium dual core 2.0 GHz
 - 1 GB Memory
- Delay
 - Ping test
 - RTT: ~10 msec
- Throughput
 - ~1 Mbps (without any MAC protocol)



Implementation of CR Network

◆ Demo Environment

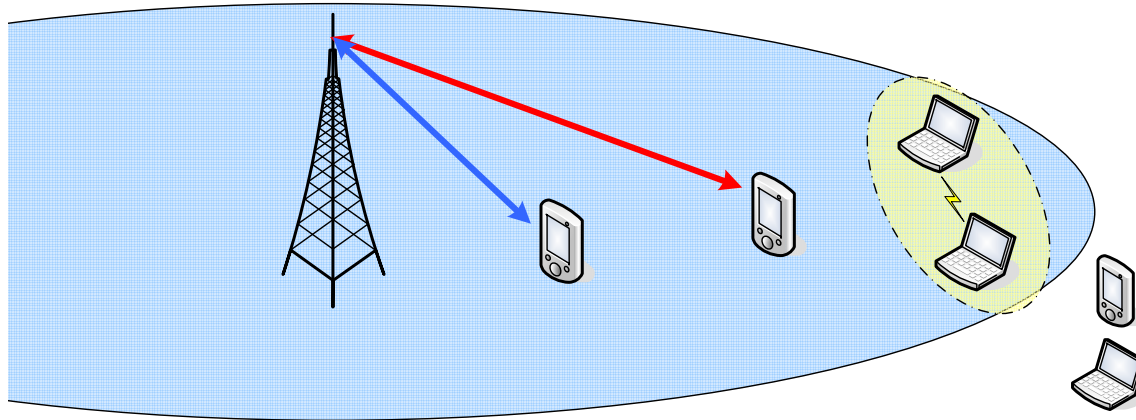
- Operating frequency band: 1.3 GHz
- Bandwidth: 8 MHz
- Modulation: DBPSK
- Bit-rate: 300 kb/sec
- Primary network
 - Cellular network: 1 BS, 2 Primary user
 - Polling MAC
- Secondary network
 - Uplink bandwidth sharing
 - Underlay communication & Overlay communication



Implementation of CR Network

◆ Demo Topology

- Band sharing illustration



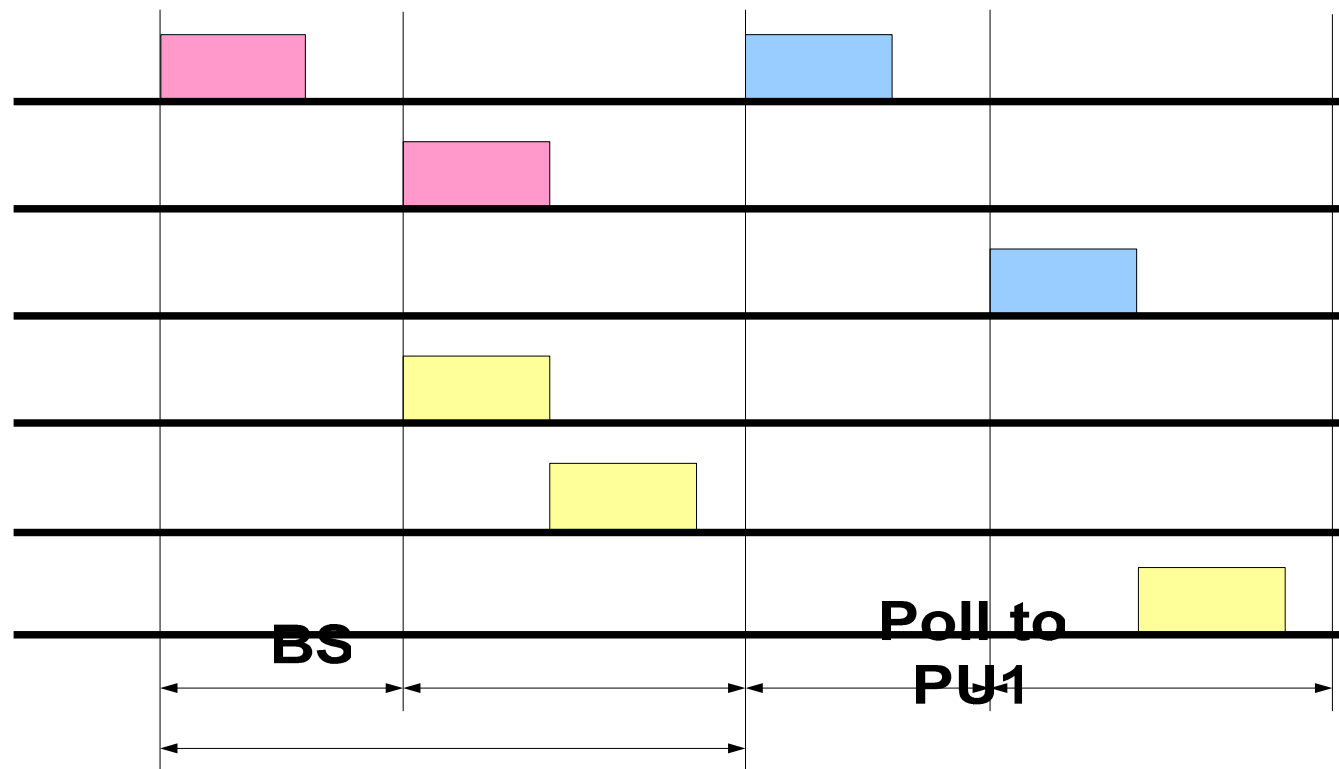
- Implementation



Implementation of CR Network

◆ Demo Scenario

- Primary traffic pattern: CBR (8 kbps for each PU, 16 kbps for BS)
- Secondary users: Using ARQ for error recovery



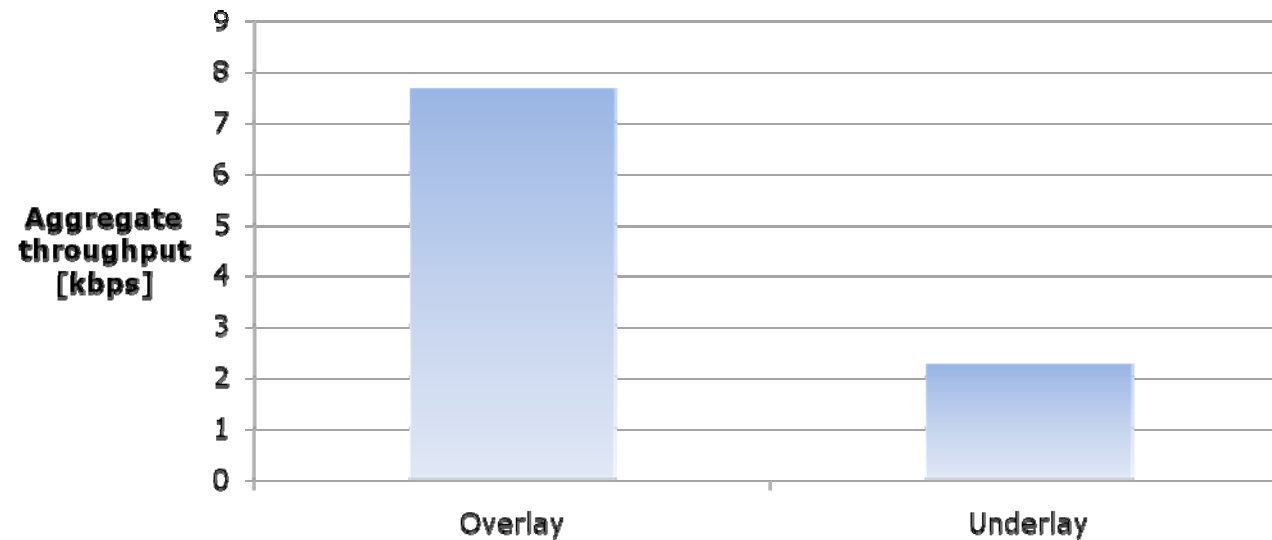
PU1

Pkt

Implementation of CR Network

◆ Demo Results

- Aggregate throughput of primary users and CR users
 - Primary network: 32 kbps
 - Secondary
 - Overlay communication: 7.67 kbps
 - Underlay communication: 2.28 kbps



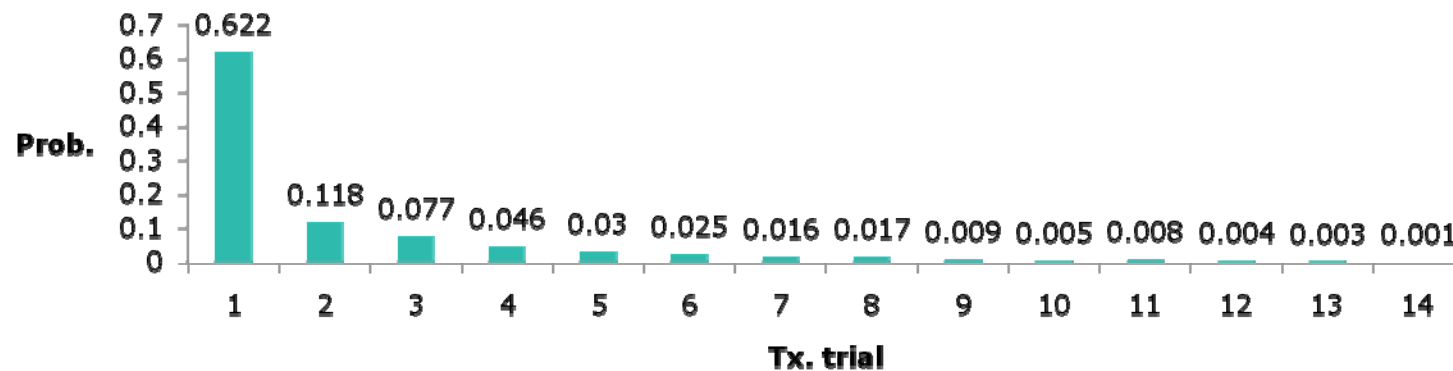
Implementation of CR Network

◆ Demo Results

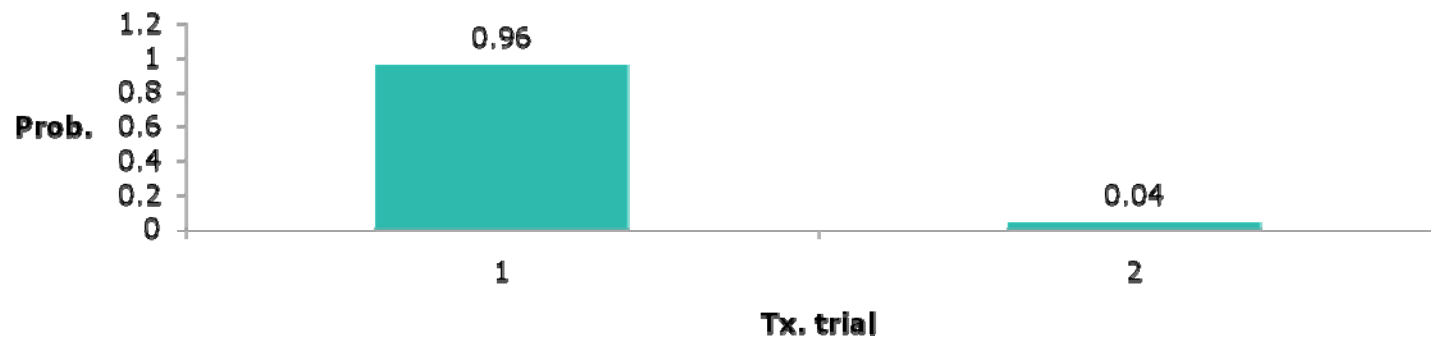
■ Transmission trial of secondary user

■ PDF of transmission trial

■ Underlay communication: Average 2.56 trial/successful Tx.



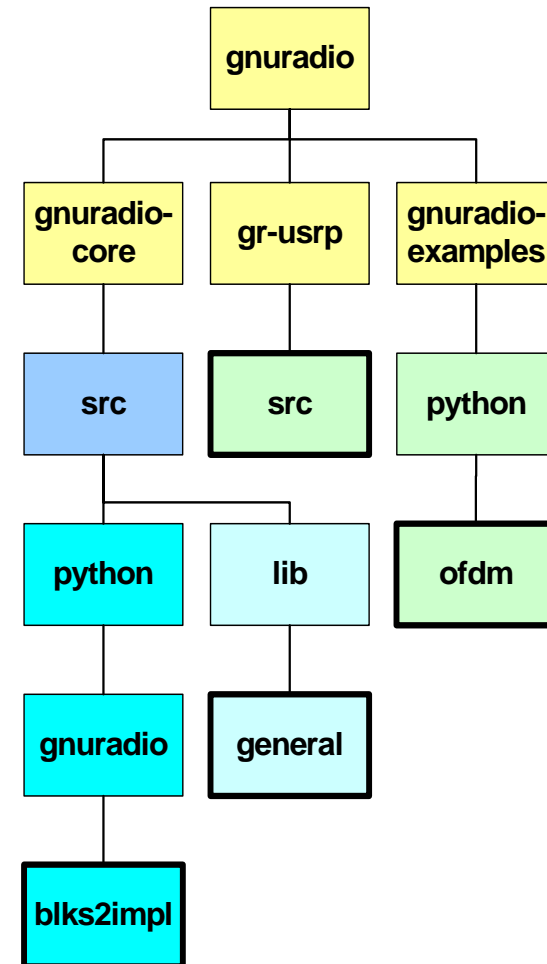
■ Overlay communication: Average 1.04 trial/successful Tx.



Implementation of OFDM

◆ OFDM

- Parameters
 - Packet size
 - Operating frequency band
 - Transmit power
 - Modulation
 - FPGA interpolation/decimation rate
 - FFT length
 - Occupied tones
 - CP length



Implementation of OFDM

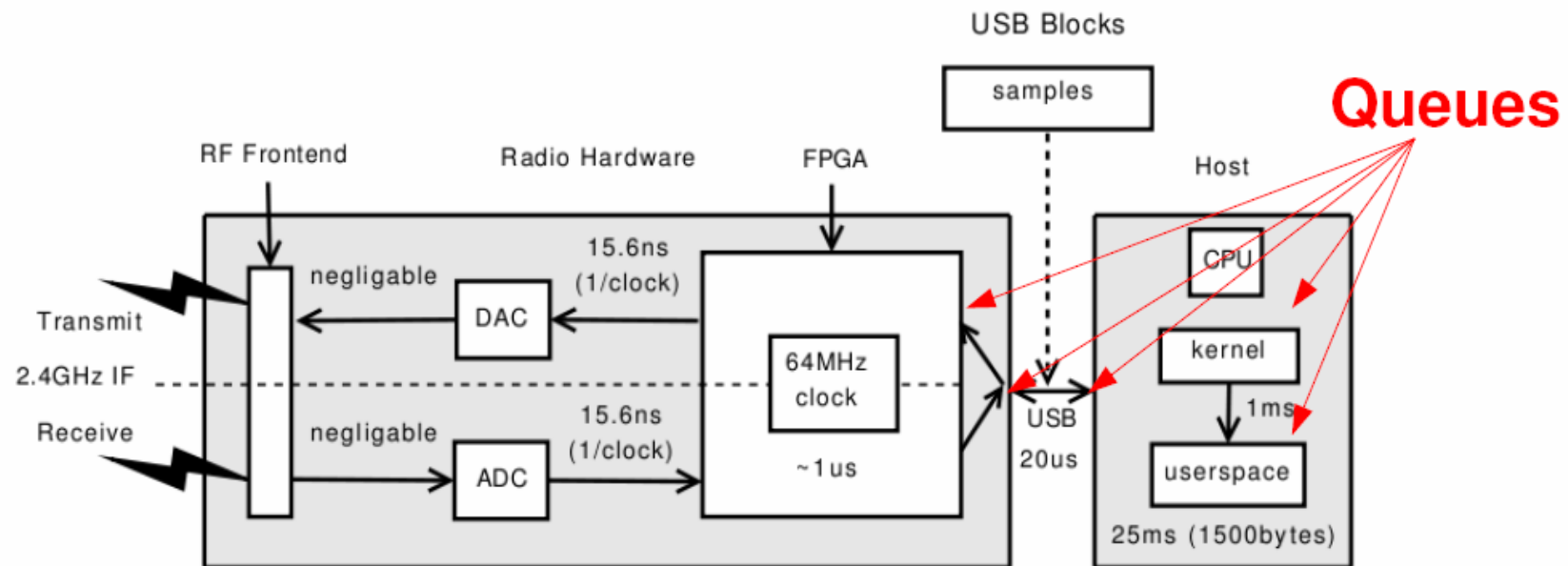
◆ OFDM

- Measurements of available operating point
 - Interpolation rate: 128~512
 - Decimation rate: 64~256
 - FFT length: ~1024
 - Occupied tones: ~800
- Maximum throughput
 - 1024 FFT with 800 occupied tones
 - 128 interpolation
 - Modulation: QPSK
 - ➔ ~1.28 Mbps

Limitation of GNU Radio

◆ Long & Unpredictable Processing Delay

- It may cause critical problems in
 - MAC protocol which requires fine time synchronization
 - Dynamic control using feedback information
 - Time varying environments



Limitation of GNU Radio

◆ Unknown Tx. Power

- We know digital amplitude at ADC/DAC only
 - 2 bytes value (0~32000)
- Actual Tx. power depends on USRP, daughter board, antenna, and host computer
 - To know real Tx. power, we should measure Tx. power at the RF frontend

◆ Insufficiency of packet-based concept

- Message blocks (M-blocks)
 - GNU Radio extension that allows more natural handling of a packet-based data
 - However, GNU radio does not fully support this yet
 - It will be new feature of release-3.2

Concluding Remark

◆ Conclusion

- GNU Radio gives us a lot of flexibility to implementing SDR
 - OFDM, MIMO
 - Flexible MAC
 - Hydra
 - 802.11 like system with time scaling (slot time = 10 ms)
- However, GNU Radio has some limitations
 - Long and unpredictable delay
 - Uncertain operation of USRP
 - Insufficiency of packet-based concept
- For more information, please refer to
 - GNU Radio homepage: <http://gnuradio.org>
 - GNU Radio forum: <http://www.nabble.com/GnuRadio-f1878.html>



Thank You !

Any Questions?